

**COMPILED & CIRCULATED BY**  
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*Topic:*

Matrix: Addition and Multiplication of Matrices. Null Matrices. Diagonal, Scalar and Unit Matrices, Upper-Triangular and Lower-Triangular Matrices, Transpose of a Matrix, Symmetric and Skew-Symmetric Matrices, Conjugate of a Matrix, Hermitian and Skew-Hermitian Matrices, Singular and Non-Singular matrices, Orthogonal and Unitary Matrices, Trace of a Matrix.

**MATRICES**

**1. Objective & Relevance of the Section:**

The arrangement of a system of numbers  $mn$  in rectangular form in  $m$ - rows along with  $n$ - columns and finally bounded by a [ ] bracket is called a **Matrix (plural form matrices)**. Matrices are used in the study of electrical circuits, quantum mechanics, optics, solving of differential equations, etc. A matrix with the same number of rows and columns, sometimes used to represent a linear transformation from a vector space to itself, such as reflection, rotation, or shearing.

Example:  $[A] = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

In this section, our main objective is to learn the Addition and Multiplication of Matrices. Null Matrices. Diagonal, Scalar and Unit Matrices, Upper-Triangular and Lower-Triangular Matrices, Transpose of a Matrix, Symmetric and Skew-Symmetric Matrices, Conjugate of a Matrix, Hermitian and Skew-Hermitian Matrices, Singular and Non-Singular matrices, Orthogonal and Unitary Matrices, Trace of a Matrix as per CBCS syllabus of C&T of Physics (H) under Vidyasagar University.

**2. Concept of different Matrices:**

**Row Matrix:**  $[A] = [1 \ 2 \ 3]$

**Column Matrix:**  $[A] = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

**Null Matrix:**  $[A] = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

A matrix with all elements are zero is called a null matrix.

**Diagonal Matrix:**  $[A] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

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A square matrix with all the non-diagonal elements are zero is called a diagonal matrix. If all the diagonal elements are "1". Then, the matrix is called Unit or Identity Matrix.

$$\text{Unit or Identity Matrix: } [A] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\text{Singular Matrix: } [A] = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}$$

A square matrix is called singular matrix if its determinant  $\det A$  is zero. If  $\det A$  is not zero the matrix  $[A]$  is called non-singular matrix.

$$\text{Non-Singular Matrix: } [A] = \begin{bmatrix} 2 & 2 & 3 \\ 2 & 6 & 4 \\ 3 & 4 & 5 \end{bmatrix}$$

$$\text{Upper Triangular Matrix: } [A] = \begin{bmatrix} 2 & 2 & 3 \\ 0 & 6 & 4 \\ 0 & 0 & 5 \end{bmatrix}$$

If all the elements of a matrix  $[A]$  below the leading diagonal of a square matrix are zero, then it is called an upper triangular matrix.

$$\text{Lower Triangular Matrix: } [A] = \begin{bmatrix} 2 & 0 & 0 \\ 2 & 6 & 0 \\ 3 & 4 & 5 \end{bmatrix}$$

If all the elements of a matrix  $[A]$  above the leading diagonal of a square matrix are zero, then it is called a lower triangular matrix.

$$\text{Symmetric Matrix: } [A] = \begin{bmatrix} a & h & g \\ h & p & f \\ g & h & c \end{bmatrix}$$

A square matrix is called a symmetric matrix if for all values of  $i$  and  $j$ ,  $a_{ij} = a_{ji}$  or  $A' = A$ . i.e. After interchanging the row and column we get the same matrix.

$$\text{Skew-Symmetric Matrix: } [A] = \begin{bmatrix} 0 & -h & -g \\ h & 0 & -f \\ g & f & 0 \end{bmatrix}$$

A square matrix is called a symmetric matrix if for all values of  $i$  and  $j$ ,  $a_{ij} = -a_{ji}$  or  $A' = -A$ .

### Transpose of Matrix:

If the rows and the corresponding columns of a matrix  $A$  are interchanged, then the resulting matrix is called the transpose of the matrix  $A$  and denoted by  $A'$ .

$$[A] = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \text{ and } [A]' = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix}$$

If  $A' = A$ ; then the matrix is called symmetric matrix. Otherwise, if  $A' = -A$ ; then the matrix is called skew symmetric matrix.

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### Orthogonal Matrix:

A square matrix A is said to be orthogonal if,  $A'A=I$ .

$$[A] = \begin{bmatrix} \cos\alpha & -\sin\alpha \\ \sin\alpha & \cos\alpha \end{bmatrix} \text{ Therefore, } [A]' = \begin{bmatrix} \cos\alpha & \sin\alpha \\ -\sin\alpha & \cos\alpha \end{bmatrix}$$

$$\text{Then, } [A]'[A] = \begin{bmatrix} \cos\alpha & \sin\alpha \\ -\sin\alpha & \cos\alpha \end{bmatrix} \begin{bmatrix} \cos\alpha & -\sin\alpha \\ \sin\alpha & \cos\alpha \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

### Conjugate Matrix:

If the elements of a matrix are complex, then, its conjugate is represented by  $A^*$

$$[A] = \begin{bmatrix} 1+i & 2+3i \\ 1-i & 2-3i \end{bmatrix} \text{ then } A^* = \begin{bmatrix} 1-i & 2-3i \\ 1+i & 2+3i \end{bmatrix}$$

### Hermitian Matrix:

A square matrix  $A = [a_{ij}]$  is called hermitian, if every  $ij$ th element of A is equal to complex conjugate of  $j$ th element of A. i.e.  $a_{ij} = a_{ji}^*$

$$[A] = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \text{ then } [A]^* = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

### Skew-Hermitian Matrix:

A square matrix  $A = [a_{ij}]$  is called skew-hermitian, if every  $ij$ th element of A is equal to negative conjugate complex of  $j$ th element of A. i.e.  $a_{ij} = -a_{ji}^*$

$$[A] = \begin{bmatrix} i & 2-3i & 4+5i \\ -2-3i & 0 & 2i \\ -4+5i & 2i & -3i \end{bmatrix}$$

Here,  $[A]^* = -A$

**Unitary Matrix:** If,  $[A]^*A = I$ , then [A] is called Unitary Matrix.

$$\text{Matrix Addition: } [A] + [B] = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 3 \\ 2 & 2 & 4 \\ 3 & 3 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 3 & 6 \\ 4 & 5 & 8 \\ 6 & 7 & 7 \end{bmatrix}$$

**Matrix Addition is commutative:**  $A+B = B+A$

**Matrix Addition is associative:**  $A+(B+C) = (A+B)+C$

### Matrix Multiplication:

$$[A] \times [B] = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \times \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} ae+bg & af+bh \\ ce+dg & cf+dh \end{bmatrix} = AB$$

### Trace of Matrix:

Trace means sum of diagonal elements.

$$[A] = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}$$

$$\text{Trace of } [A] = \text{Trace of } \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix} = 9$$

The trace of the product of two matrices [A] and [B] is independent of multiplication.

$$\text{i. e. } T_r [AB] = T_r [BA]$$

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### 3. Summary:

Herein, we learn the Addition and Multiplication of Matrices, Null Matrices, Diagonal, Scalar and Unit Matrices, Upper-Triangular and Lower-Triangular Matrices, Transpose of a Matrix, Symmetric and Skew-Symmetric Matrices, Conjugate of a Matrix, Hermitian and Skew-Hermitian Matrices, Singular and Non-Singular matrices, Orthogonal and Unitary Matrices, Trace of a Matrix 4. 4.

### Frequently Asked Questions:

a. Prove that every square matrix can be expressed as a sum of a symmetric matrix and a skew symmetric matrix.

b. Show by means of an example that in matrices  $A+B=0$  does not necessarily mean that either  $A=0$  or  $B=0$ , where 0 stands for the null matrix.

c. Express 
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 4 & 5 \\ 5 & 6 & 7 \end{bmatrix}$$
 as sum of a symmetric and a skew-symmetric matrix.

d. Prove that  $[AB]^n = A^n B^n$

e.  $A = \begin{bmatrix} 0 & 1+2i \\ -1+2i & 0 \end{bmatrix}$  show that  $U = [I-A][I+A]^{-1}$  is unitary.

f. Show that the inverse of a unitary matrix is unitary and the product of two unitary matrices is unitary.

g. Show that  $A = \begin{bmatrix} \cos\beta & -\sin\beta \\ \sin\beta & \cos\beta \end{bmatrix}$  is orthogonal.

### References:

(i) Principles of Mathematical Physics, Author- S. P. Kuila, published by NCBA (2018 Ed.).

(ii) Mathematical Physics: Author-H.K. Dass & Rama Verma, published by S. Chand (2018 Ed.).